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Mecnet

Description This website presents the principles of finite deformation continuum mechanics with many example applications to metals and incompressible viscoelastic materials (rubber). It can serve as lecture notes for a graduate level course in continuum mechanics for engineers interested in the subject.

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$dx(1)(1) \square dx(2) = dx dx(2) \cos \theta = dX \square 2 \epsilon \epsilon$
 $\square dX(2)(4.7-11)$ where θ is the angle between the deformed vectors as shown in Figure 4.3. If now we let ϵ , the angle measures the small change in the original right angle between $dX(1)$ and $dX(2)$ and also $\cos \theta = \cos \epsilon = \sin \epsilon$ since ϵ is very small for infinitesimal deformations.

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